

Construction of a Selective Compliance Articulated Robot Arm

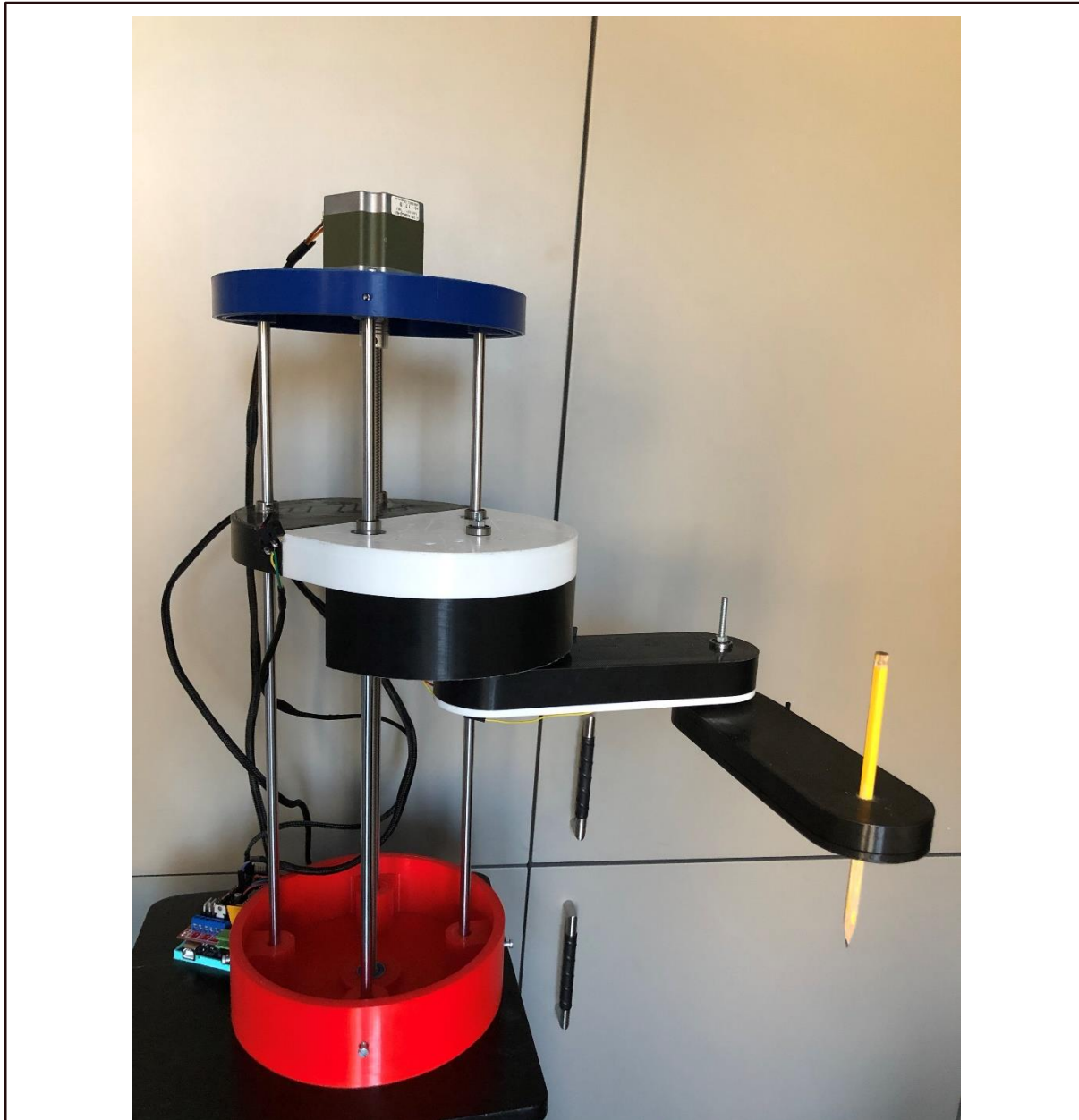
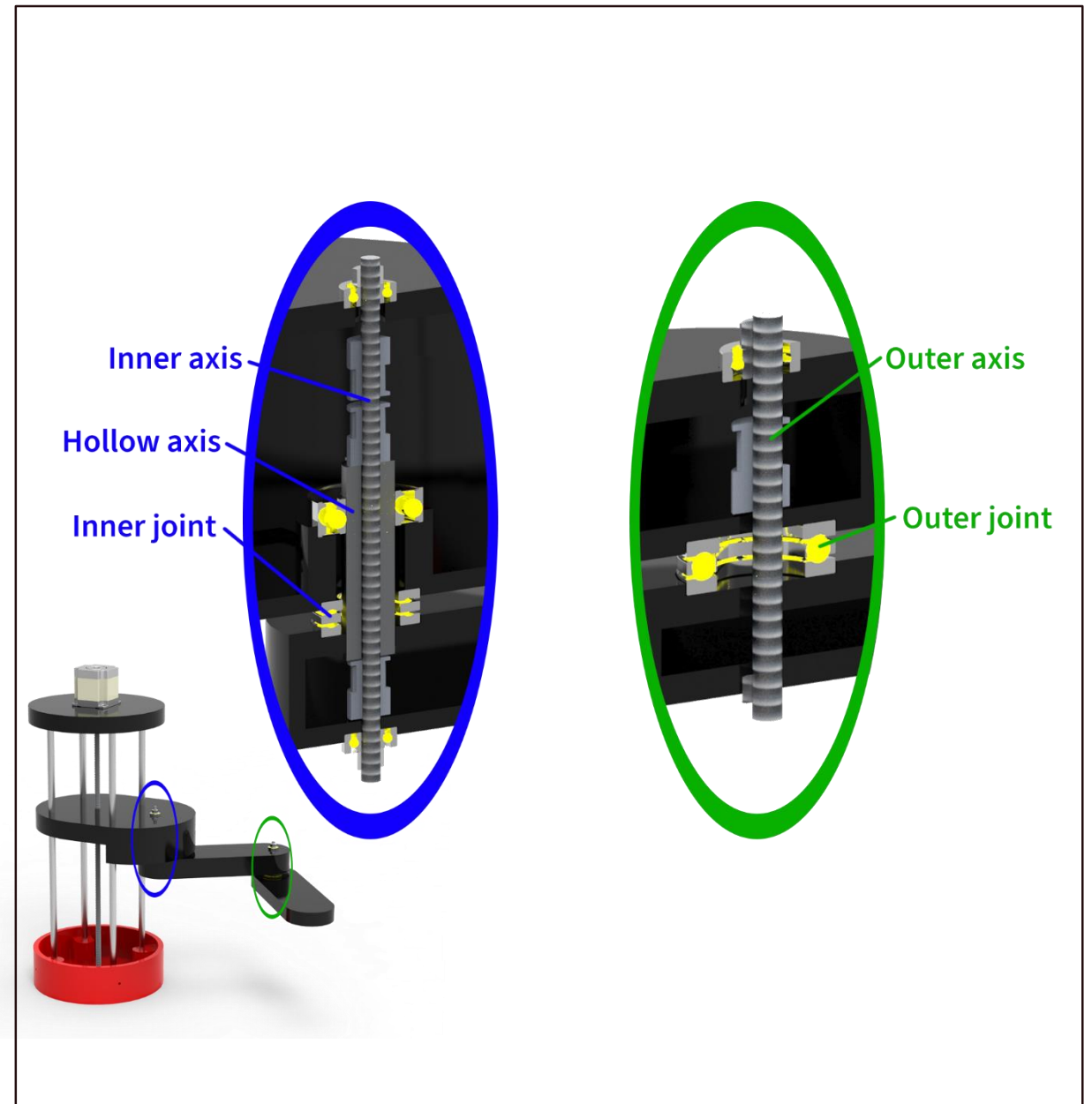
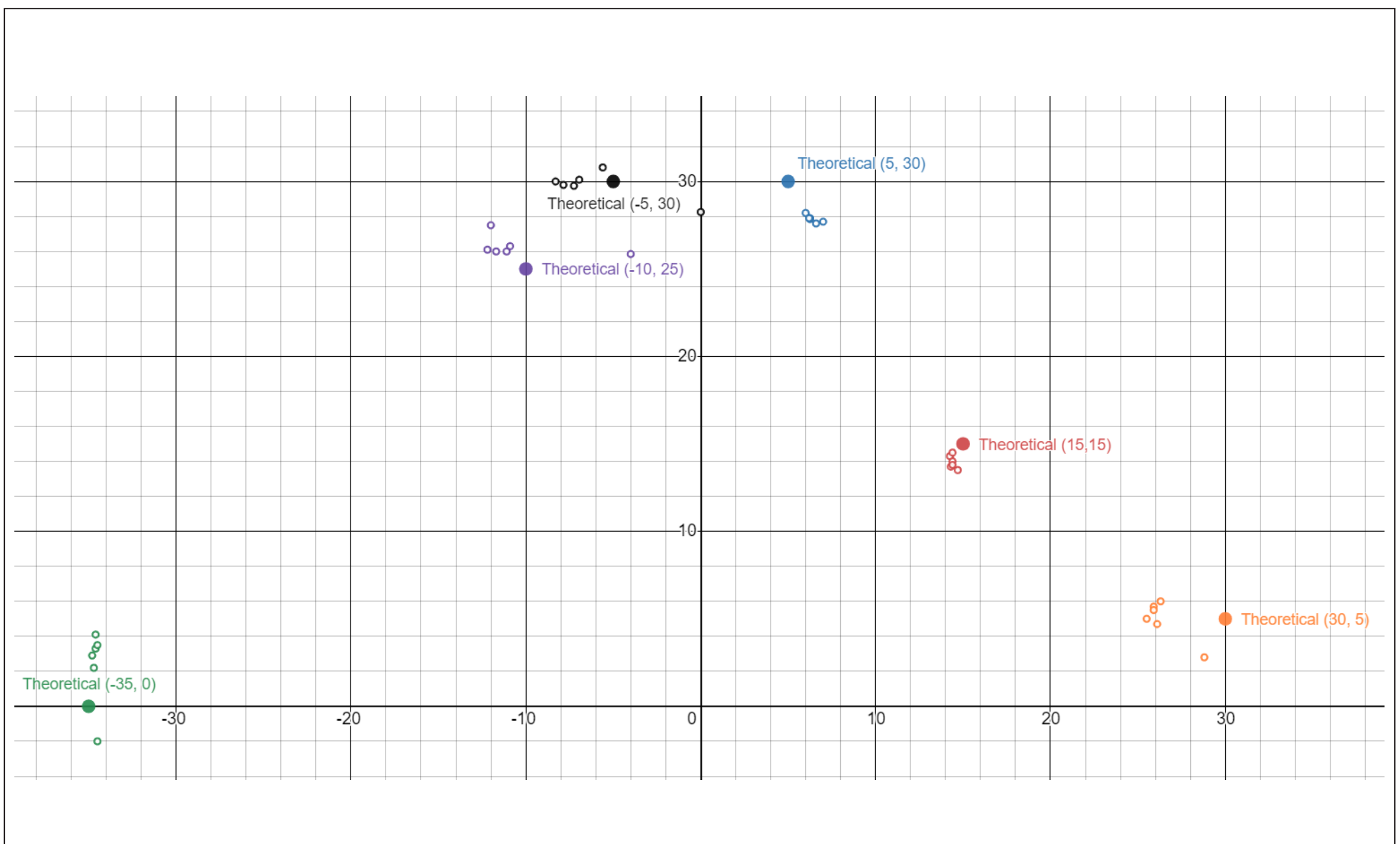


Image of the final construction featuring pencil end-effector



Centralization of motor masses around Z-axis enabled by coaxial solution



Achieved distribution from accuracy test

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och management