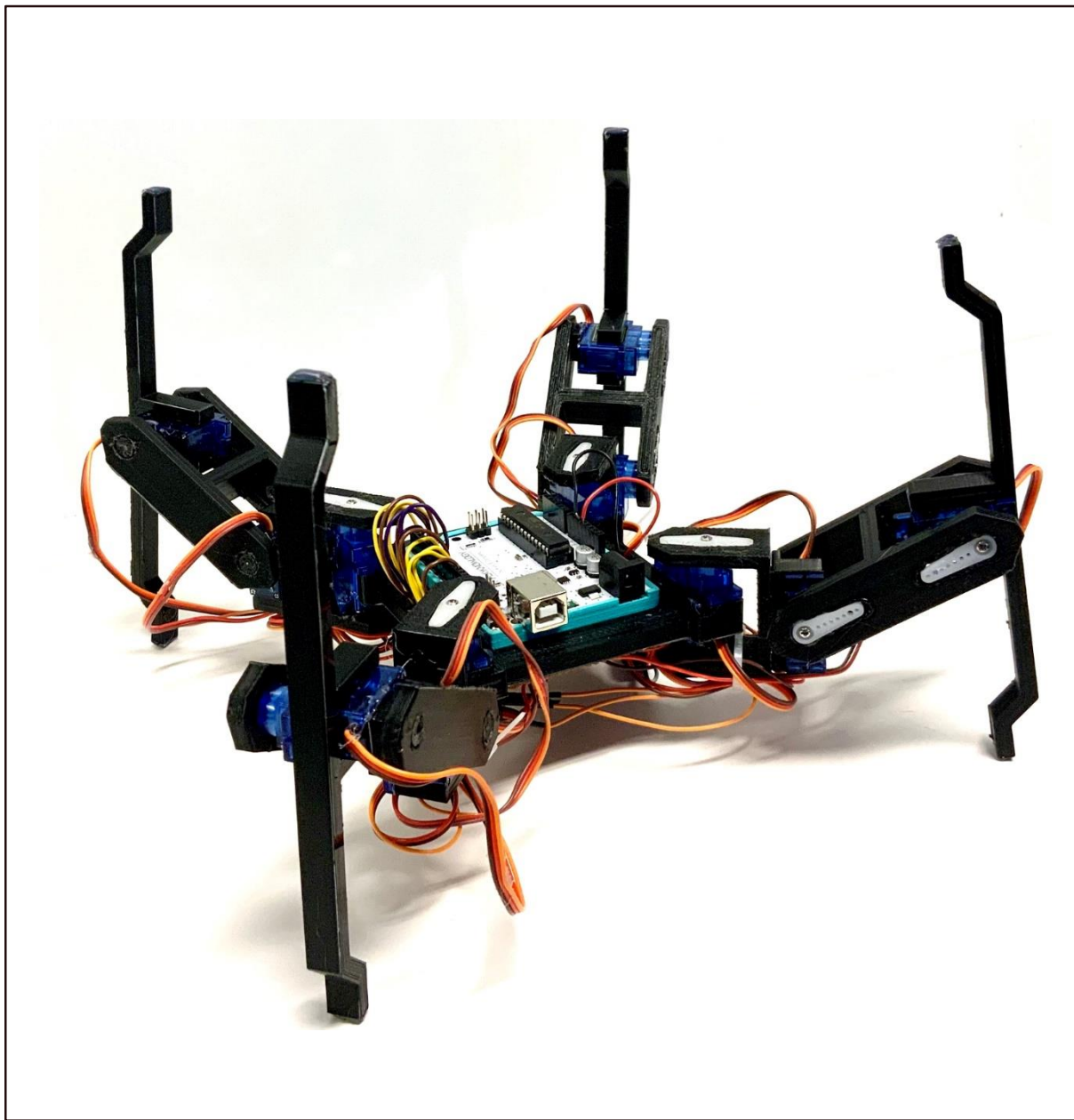
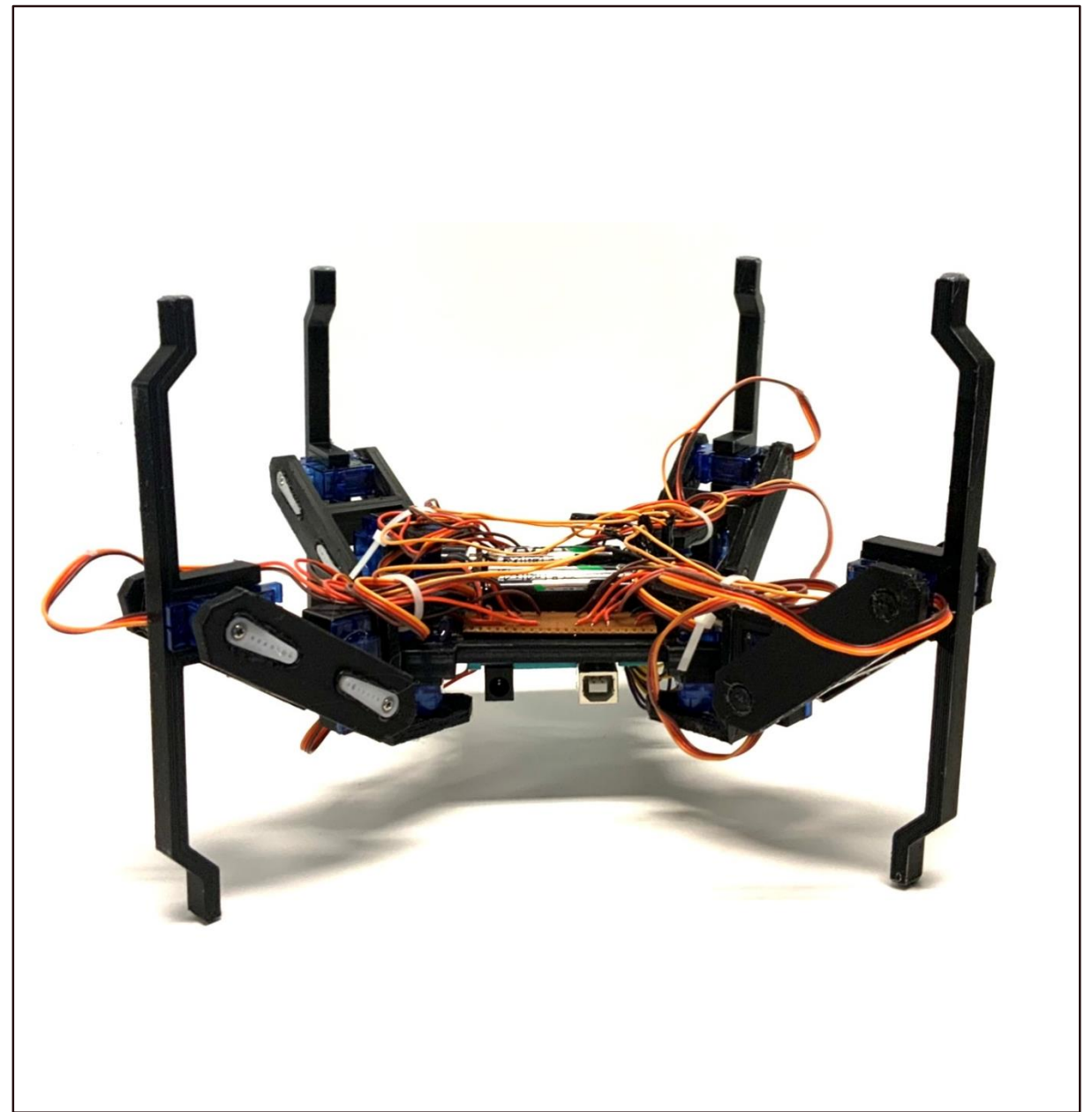


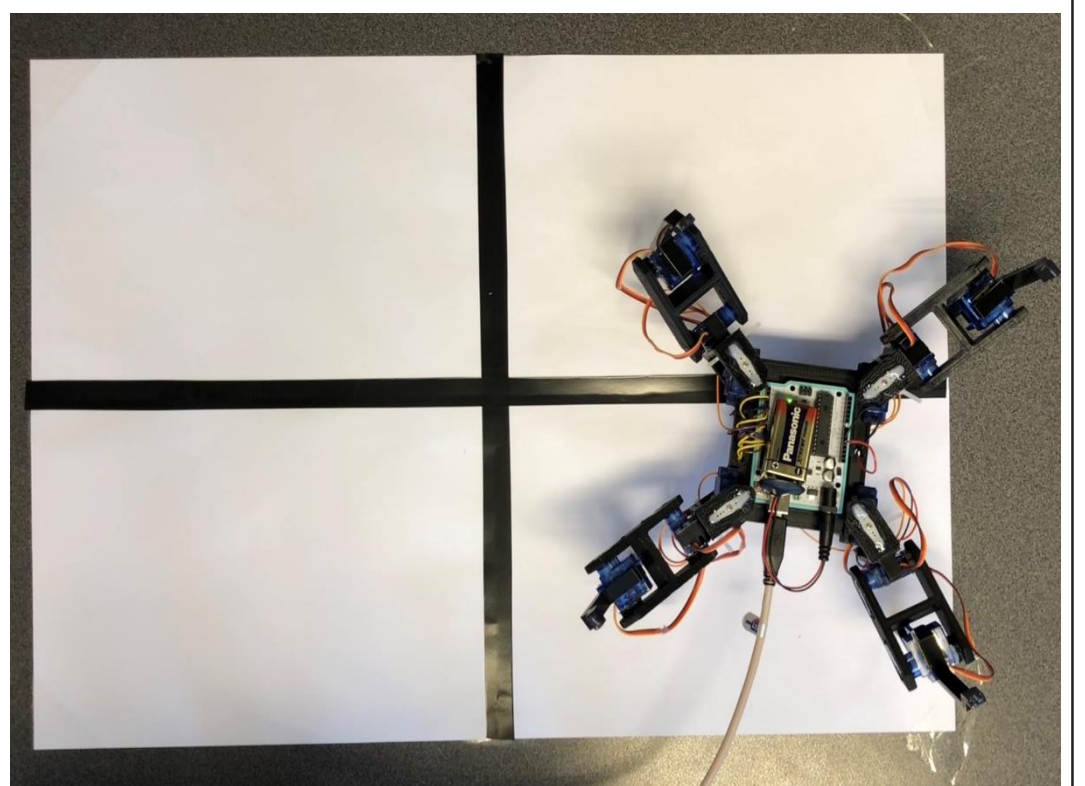
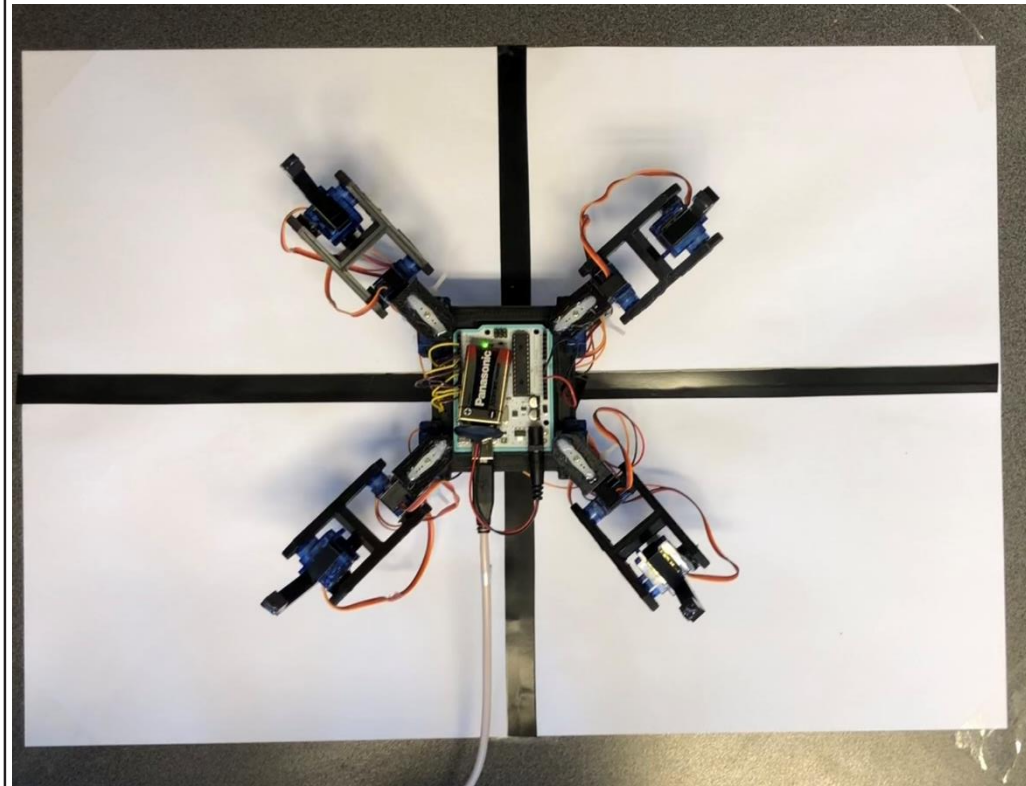
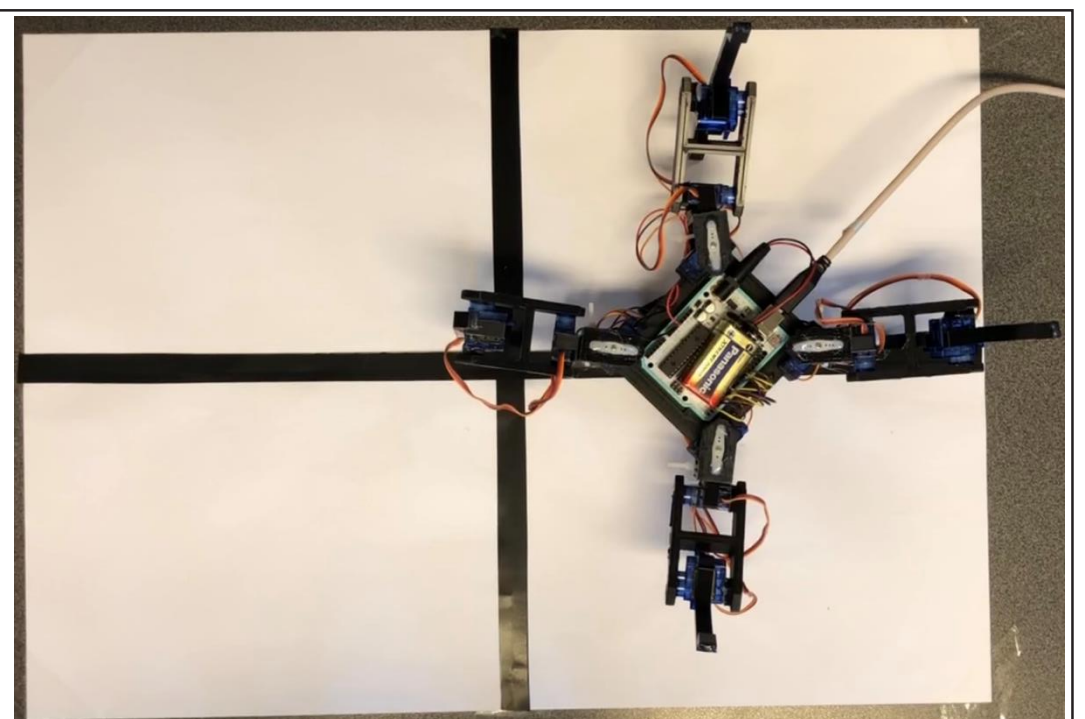
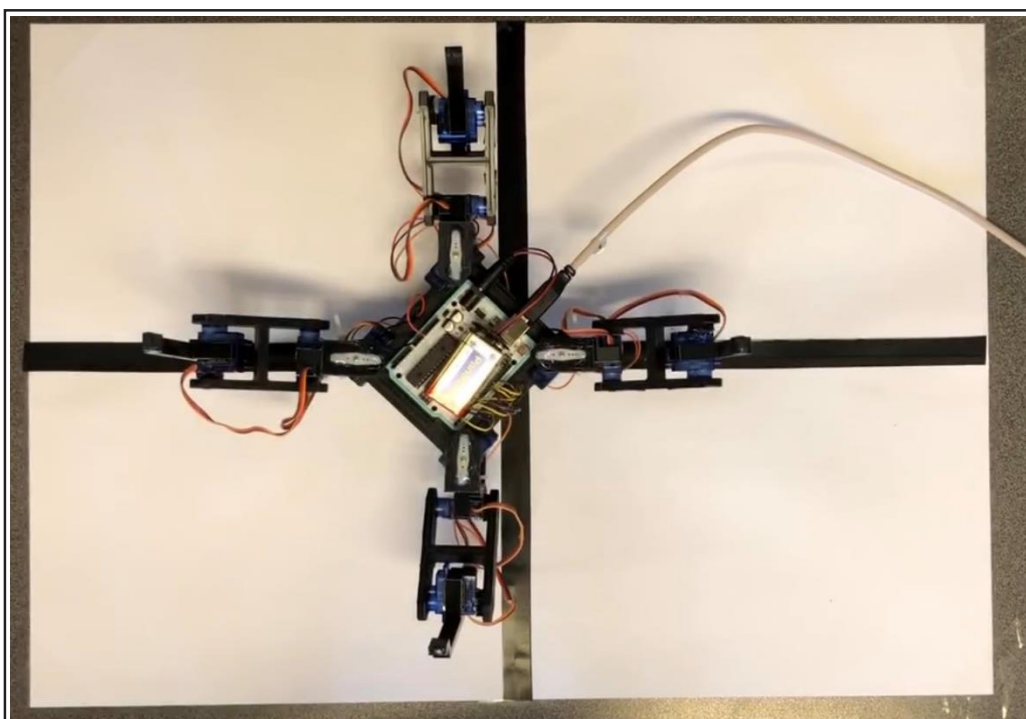
Omnidirectional Quadruped Robot



Final prototype.



Prototype has no problem standing or walking upside down thanks to symmetry.



The robot walking in the same direction independent of orientation.

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MF133X VT21
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