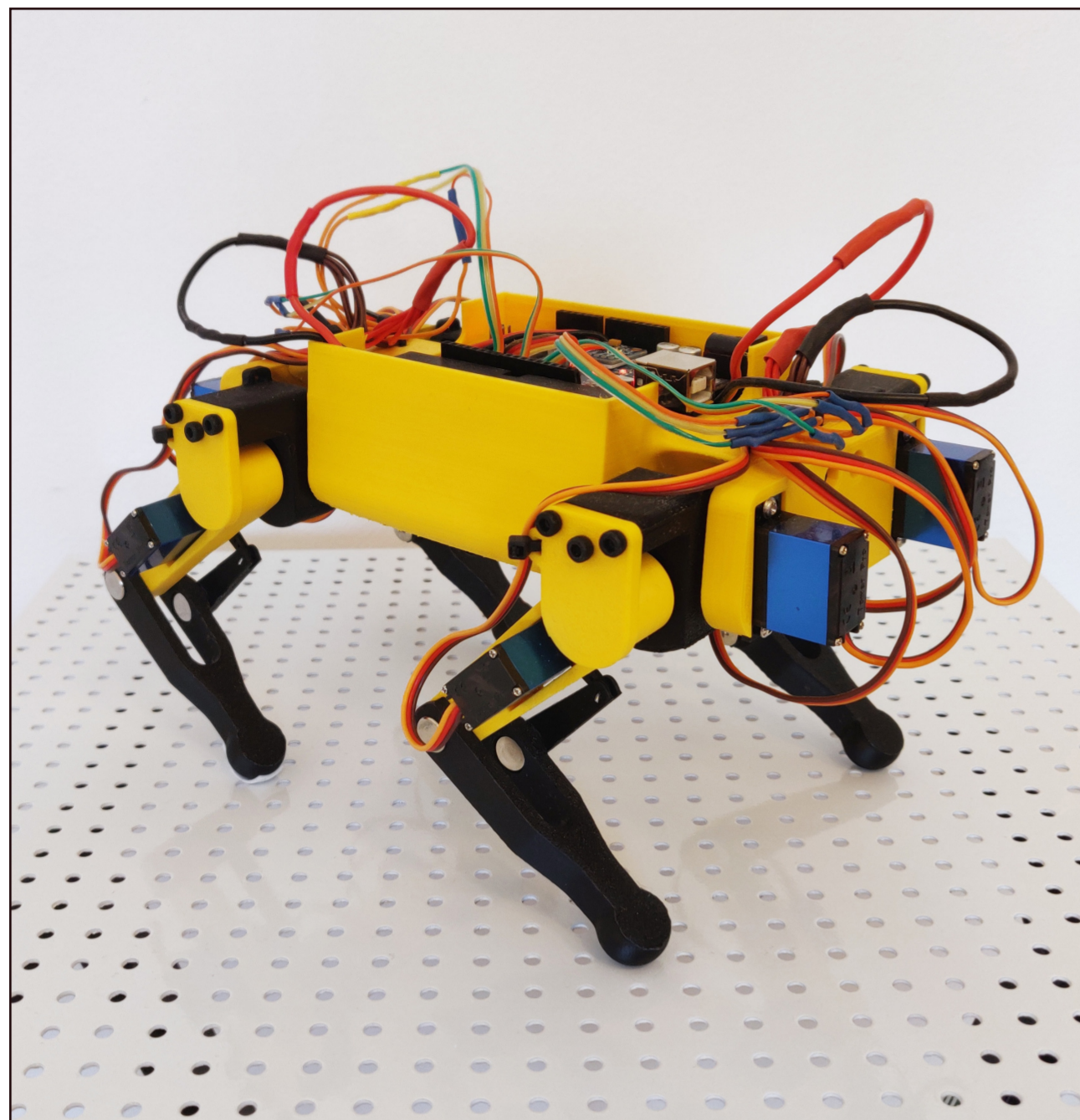
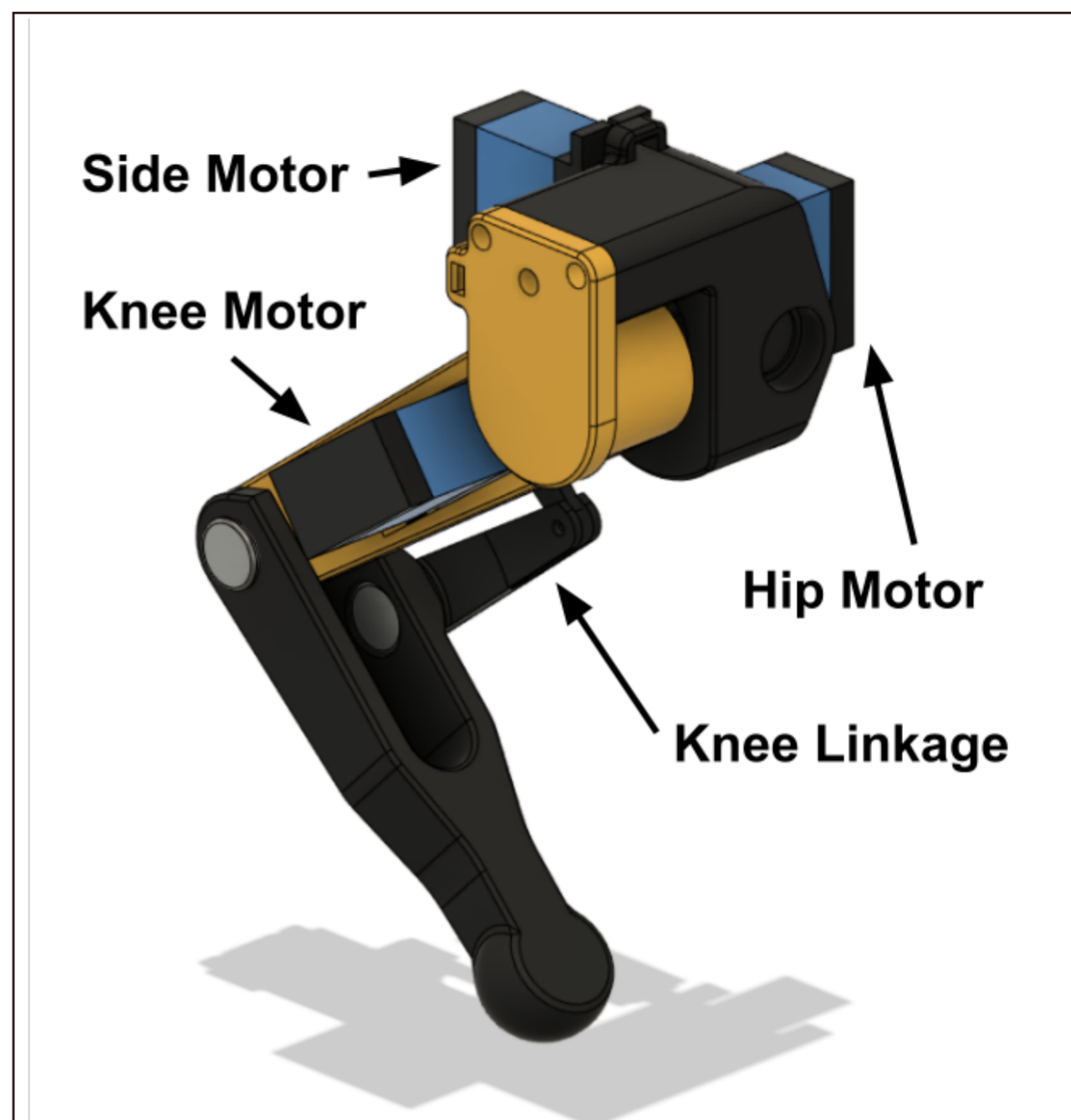


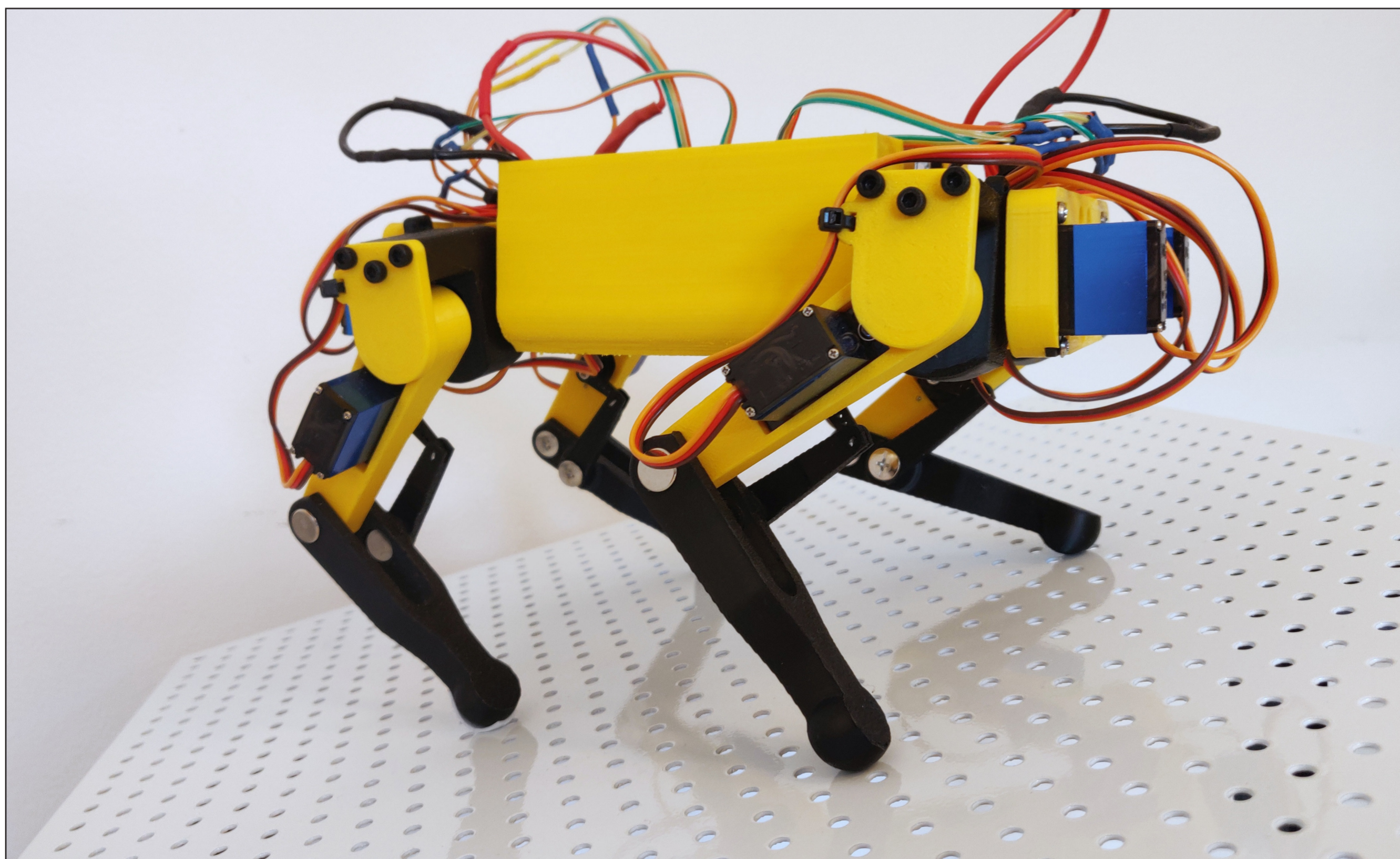
Design and Stability of a Quadruped Robot



Final prototype standing on a level surface.



CAD-model of a leg with servo motors and linkage.



Demonstration of robot function. The prototype can maintain balance when standing on varying inclines, while keeping its body level.

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